

# Manual DSE-S7



- **8 Digit SSI-display in DIN-housing 144 X 72 mm**
- **Supply voltage 10 – 35V DC**
- **2 Programmable outputs**
- **In- and outputs optically isolated**
- **Programmable multiplicator**

**Table of content**

<b>1 INTRODUCTION.....</b>	<b>3</b>
1.1 GENERAL.....	3
1.2 IMPORTANT INFORMATION.....	3
1.3 EMC MEASURES.....	4
<b>2 OPERATION.....</b>	<b>7</b>
2.1 KEY FUNCTIONS.....	7
2.2 DISPLAY FUNCTIONS.....	8
2.2.1 <i>Status functions</i> .....	8
2.2.2 <i>Error messages</i> .....	9
<b>3 PROGRAMMING .....</b>	<b>10</b>
3.1 INPUT PARAMETERS.....	10
3.2 INPUT PRESETS.....	11
<b>4 FUNCTIONS .....</b>	<b>12</b>
4.1 SSI-PROTOCOL .....	12
4.2 NUMBER OF BITS.....	12
4.3 MULTIPLICATOR .....	12
4.4 ADJUSTMENT OF THE ABSOLUTE VALUE .....	13
4.4.1 <i>Adjustment through PAR-07</i> .....	13
4.4.2 <i>Adjustment through "ZERO-SET"</i> .....	13
4.5 ZERO-SHIFT .....	13
4.6 FUNCTION INPUT.....	13
4.7 SSI-ERROR.....	14
4.8 STORE FUNCTION .....	14
<b>5 OUTPUTS .....</b>	<b>15</b>
5.1 OUTPUT PROGRAMMED AS CAM.....	15
5.1.1 <i>Example</i> .....	15
5.2 OUTPUT PROGRAMMED AS PULSE .....	16
5.2.1 <i>Example</i> .....	17

**APPENDIX A**  
**APPENDIX B**  
**APPENDIX C**  
**APPENDIX D**  
**APPENDIX E**

**PARAMETERS**  
**CONNECTIONS**  
**TECHNICAL DATA**  
**SIZES**  
**LIST OF PARAMETERS**

## 1 INTRODUCTION

### 1.1 General

The microprocessor controlled SSI-display DSE-S7 is a display for sensors, singleturn and multturn, with a SSI encoder input.

By programming several parameters the function of the unit can be determined and stored in an EEPROM.

By programming 4 presetvalues it is possible to generate different output-functions. These presetvalues are also stored in an EEPROM.

It is possible to adjust the displayed value to every desired read-out using parameters like the multiplicator and the position of the decimal point.

### 1.2 Important information

- ✓ The DSE-S7 is a high-tech electronic product. To ensure safety and a correct functioning of the product it is important that only qualified specialists will install and operate the DSE-S7.
- ✓ If through a failure or fault the DSE-S7 an endangering of persons or damage to plant is possible, this must be prevented using additional safety measures. These must remain operational in all possible modes of the DSE-S7.
- ✓ Necessary repairs to the DSE-S7 are only to be carried out by the manufacturer.

### **1.3 EMC Measures**

To ensure the best possible electromagnetic compatibility, it is recommended to pay attention to shielding and grounding the DSE-S7:

- ✓ Shielding on both sides and with the largest possible contact area.
- ✓ Keep wiring as short as possible.
- ✓ Earth-connections should be short and with the highest possible wiring-diameter.
- ✓ Signal-connections and supply-connections must be separated.

Figure 1 and 2 show the earthing when using 1 or 2 supplies. Figure 3 shows how to use the earthing strip.

Figure 1. Single supply voltage

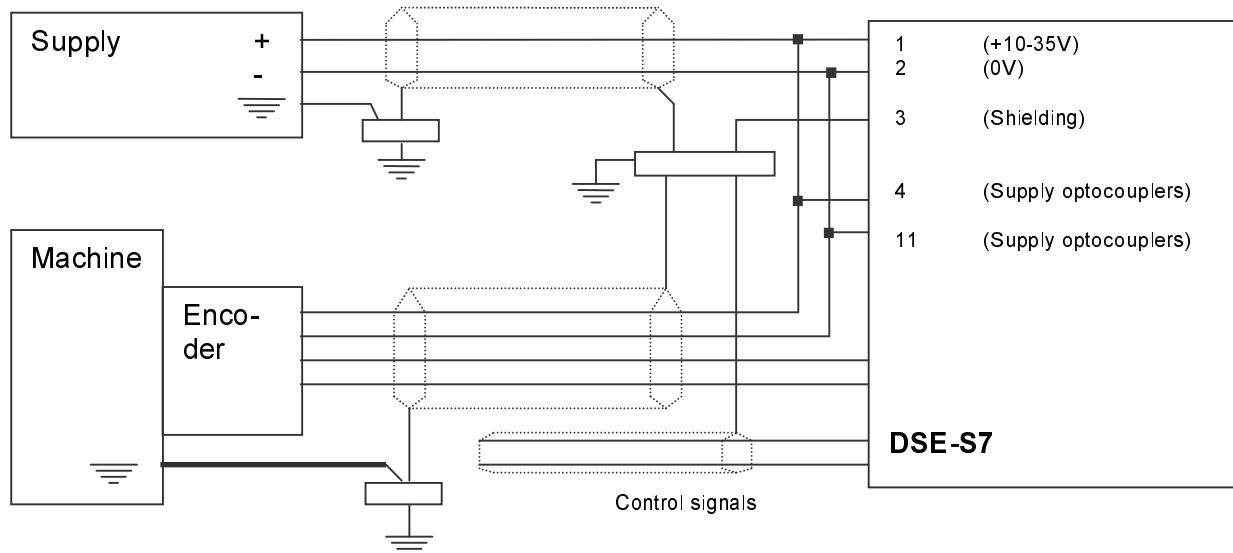


Figure 2. Double supply voltage

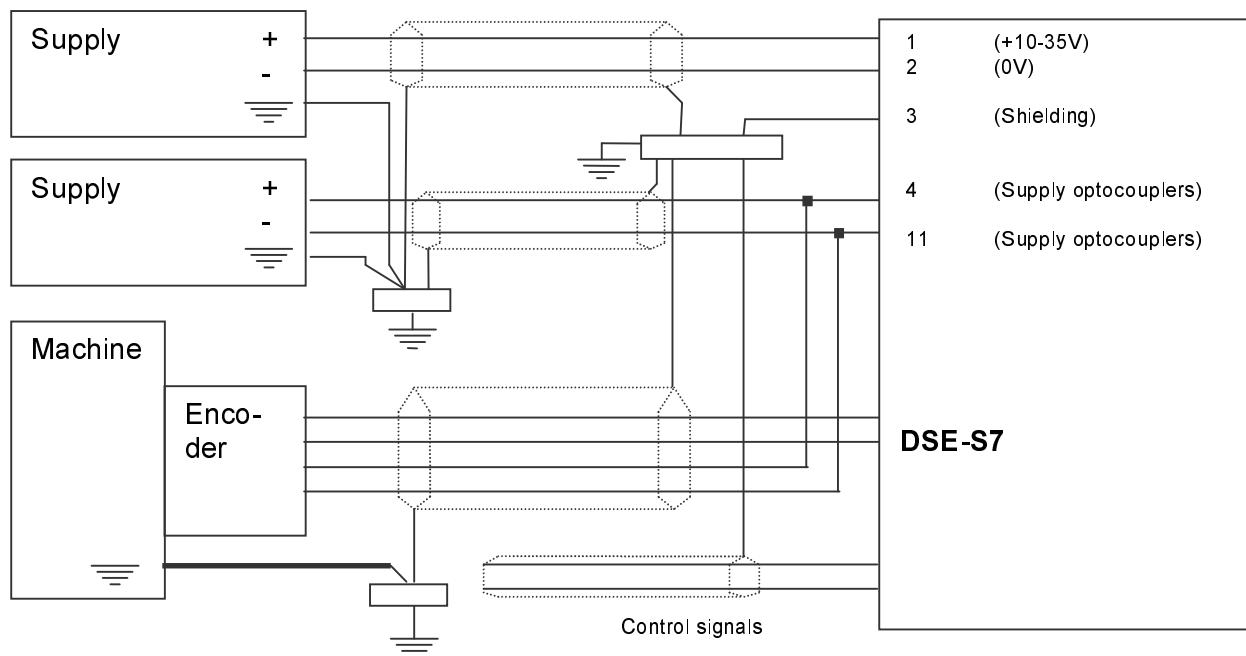
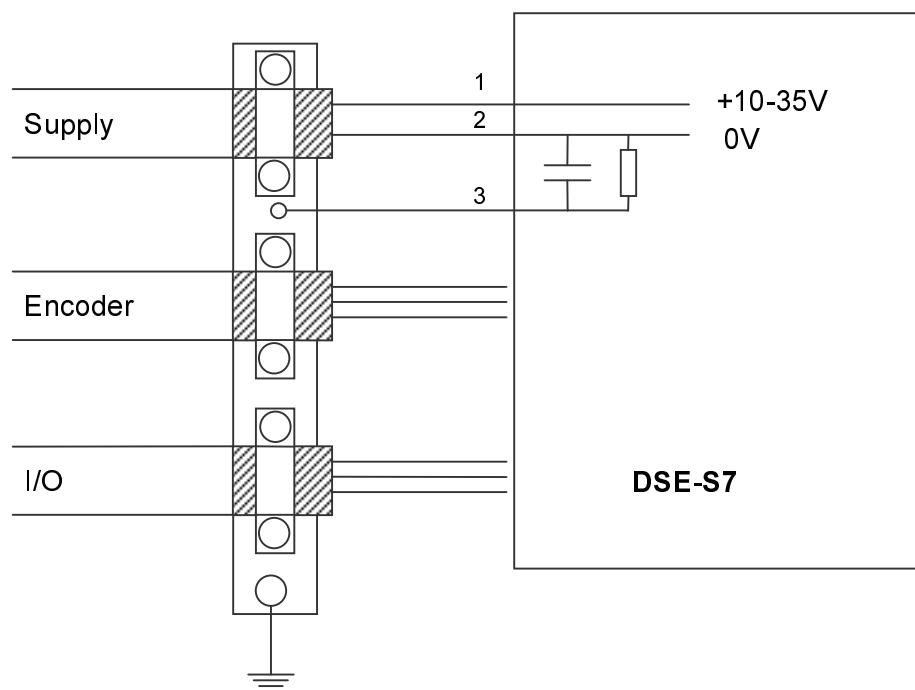


Figure 3. Shielding to earthing strip



## 2 OPERATION

### 2.1 Key functions



#### [P] Key

- activate the programming mode (in combination with other keys)
- terminate the programming mode
- leave edit mode for presets or parameters
- LED burns when edit mode for presets or parameters is active



#### [+1] Key

- view type number
- increase preset/parameter number
- increase value



#### [Cursor] Key

- view software version
- activate edit mode
- move one digit to the left in edit mode

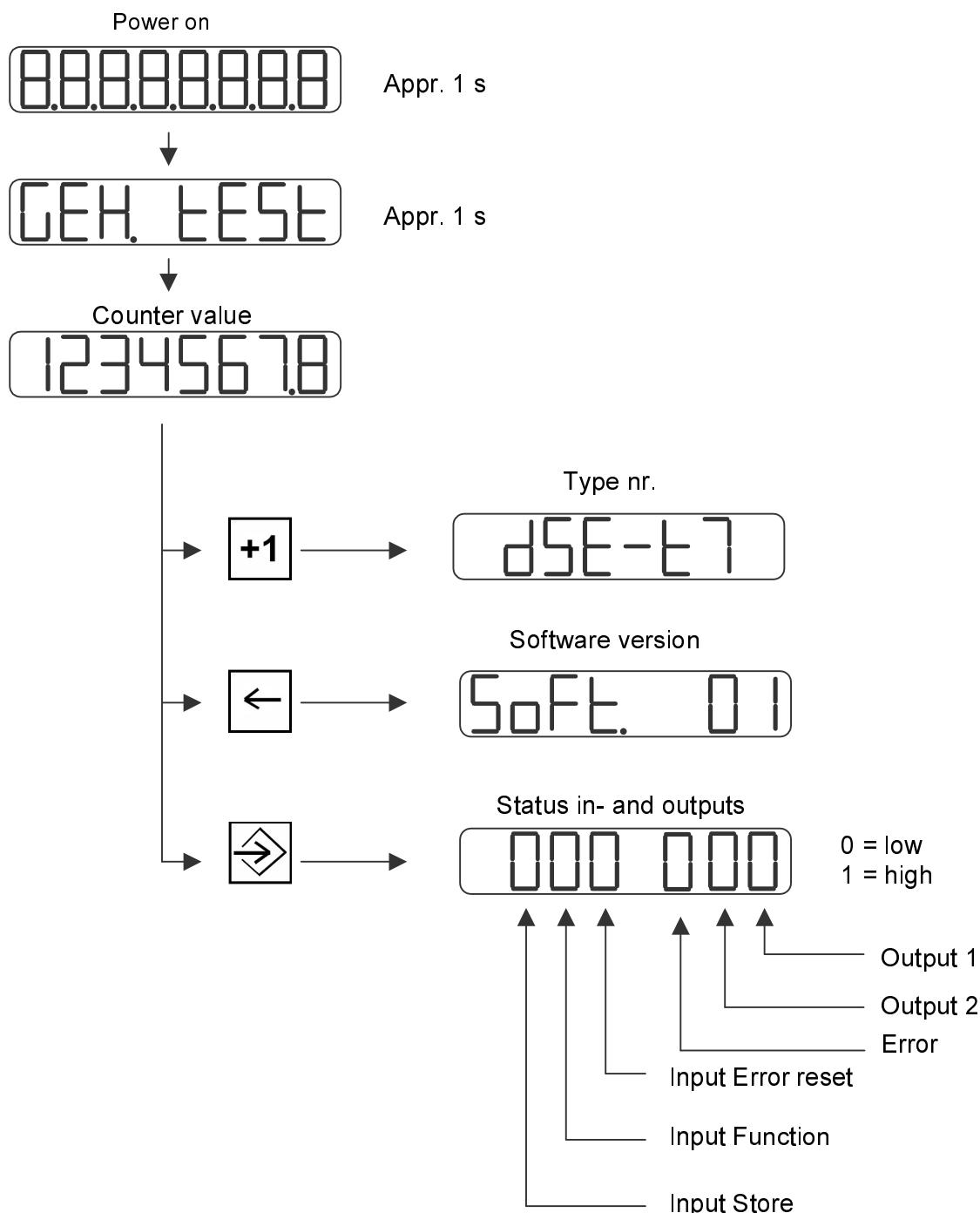


#### [Enter] Key

- store changes in programming
- view status in- and outputs
- increase preset/parameter number
- clear input (edit mode)

## 2.2 Display functions

### 2.2.1 Status functions



## 2.2.2 Error messages



SSI-communication error



Preset 2 <= preset 1



Hysteresis too big or preset 2 too small  
(preset 2 – hysteresis <= preset 1)



Preset 4 <= preset 3



Hysteresis too big or preset 4 too small  
(preset 4 – hysteresis <= preset 3)



RAM Error (replace DSE-S7)



EEPROM Error (replace DSE-S7)



No access to parameters  
(see PAR-08)



No access to presets  
(see PAR-08)



PAR-07 too big



Singleturn part PAR-04 > 13 BIT



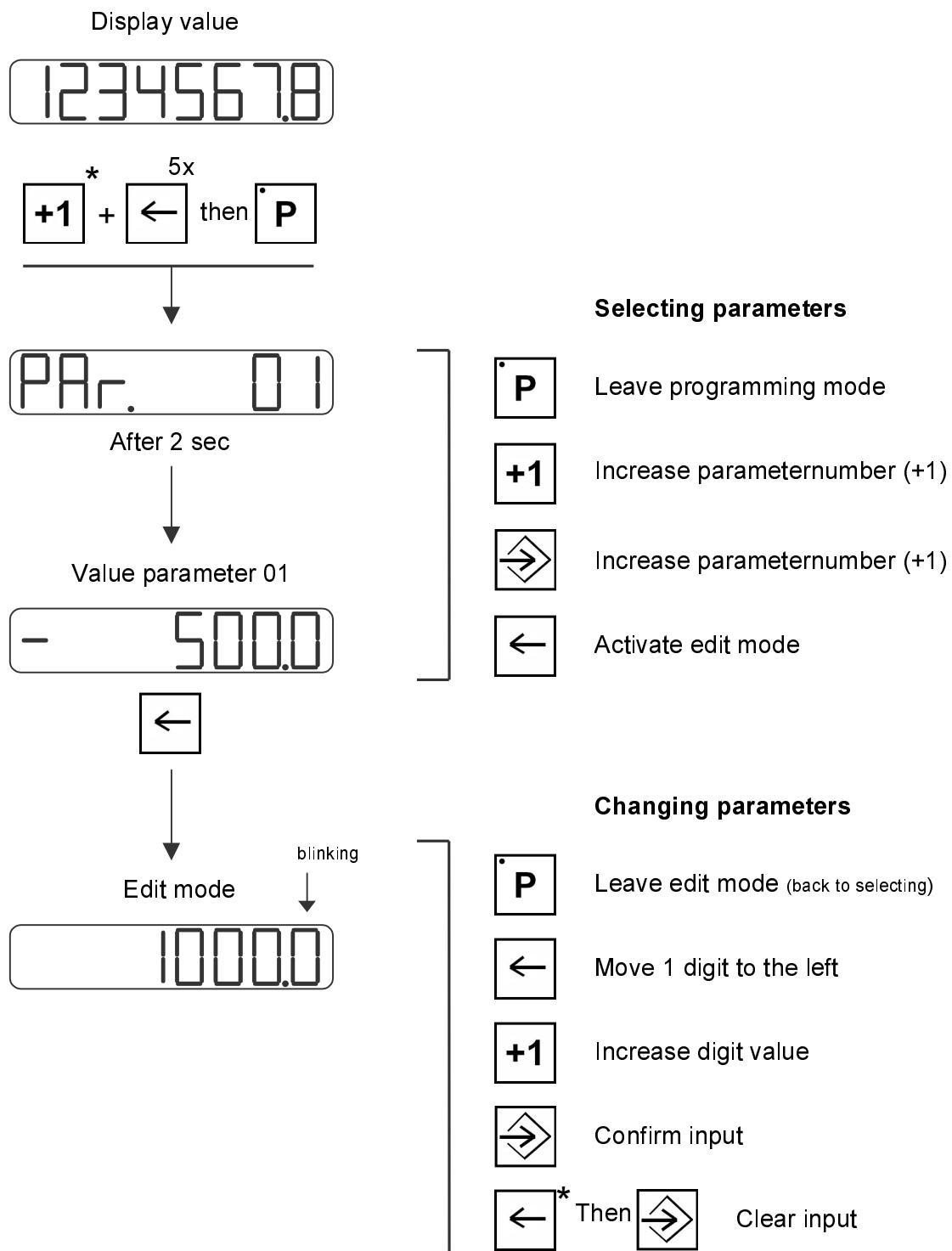
Multiturn part PAR-04 > 12 BIT



Single/Multiturn part PAR-04 = 0

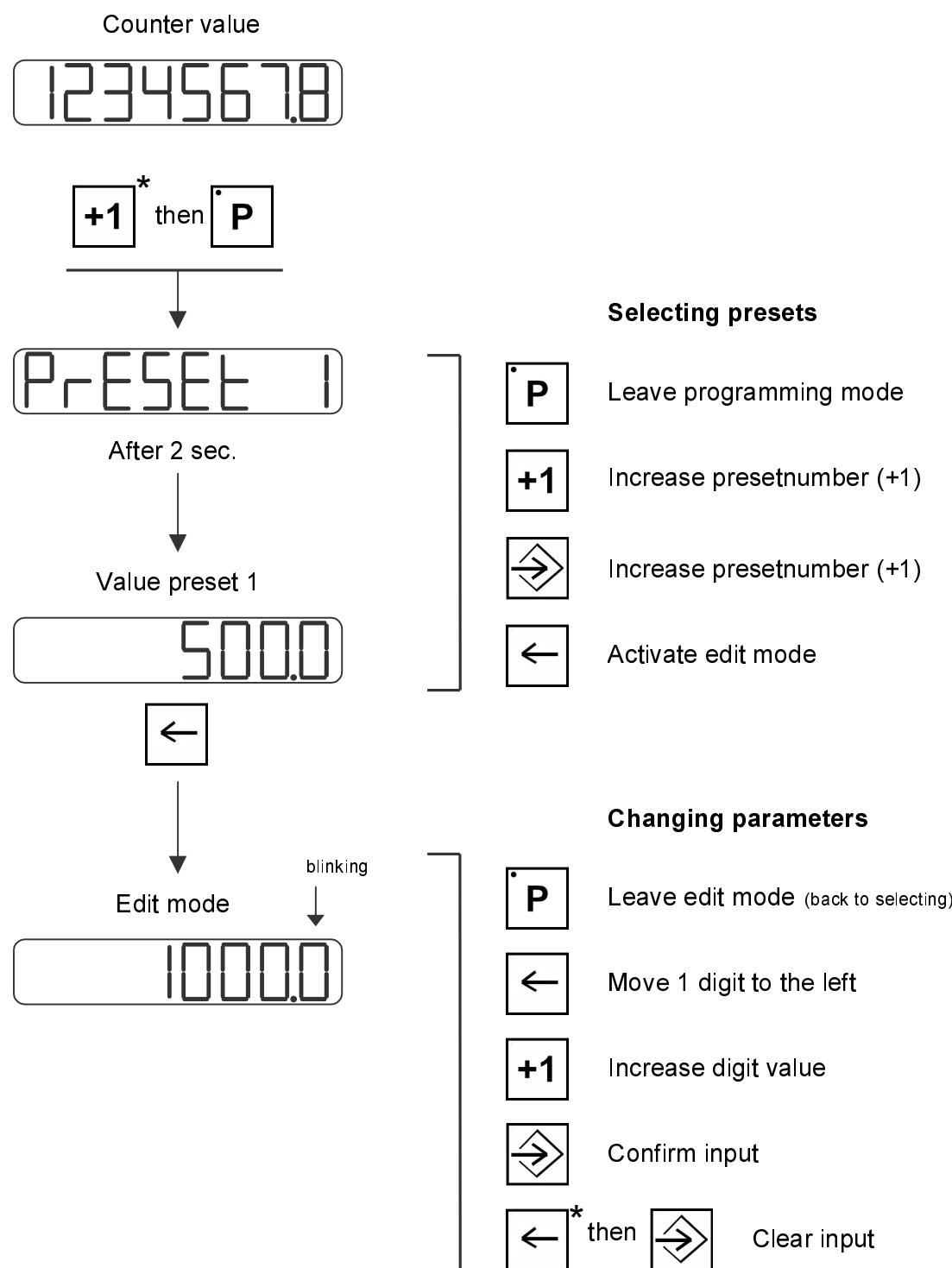
## 3 PROGRAMMING

### 3.1 Input parameters



\* keep pressed

## 3.2 Input presets



\* keep pressed

## 4 FUNCTIONS

### 4.1 *SSI-protocol*

Using this protocol the data is being transferred in Gray or Binary code. Using PAR-02 it is possible to choose between 25 bit or 13 bit. The direction can also be changed using PAR-02.

### 4.2 *Number of bits*

The encoder used determines the number of bits that can be used. In PAR-04 the number of bits that are actually used can be set.

PAR-04: XX.YY

Where      XX = number of bits multeturn part  
And          YY = number of bits singleturn part

### 4.3 *Multiplicator*

If the actual counted steps are not equal to the desired display value, the display value can be changed using the multiplicator (PAR 03).

For example:

600 steps = 50 mm displacement  
resolution = 0.1 mm

$$\text{multiplicator} = 500 / 600 = \mathbf{0,8333}$$

## **4.4 Adjustment of the absolute value**

To make an electrical adjustment of the absolute value you can choose between two possibilities. You can adjust through PAR-07 or adjust through “ZERO-SET”. Using this option means you will not have to mechanically rotate the axis of the encoder.

### 4.4.1 Adjustment through PAR-07

This is possible only if PAR-12 = 1.

The value stored in PAR-07 will be used to adjust the absolute value of the encoder. The value will be added to the encoder-value and corrected for the maximum possible display-value.

### 4.4.2 Adjustment through “ZERO-SET”

The “ZERO-SET” function is available if PAR-12 = 2.

Using this function the absolute value of the encoder can be changed to 0. To activate the adjustment a rising or falling flank at the Function input is required.

## **4.5 Zero-shift**

Using PAR-01 it is possible to add a stored value to the display-value. This off-set or zero-shift can be positive or negative.

## **4.6 Function input**

This input can be programmed with different functions using PAR-08.

### **Function 1**

“ZERO-SET” to be used for the adjustment of the absolute value. Programming a 1 or a 2 determines whether a rising or falling flank should be used.

### **Function 2**

Signal “lock programming mode” for parameters and / or presets. The programming mode can only be accessed when the input is high. PAR-08 = 3 or 4.

#### **4.7 SSI-error**

Using PAR-13 you can check the SSI-communication. With PAR-13 set to 1 the SSI-data will be displayed, regardless of the validity. If set to 0, the data will be checked. If an invalid value is detected, the SSI-data will be read once more. In case this second reading is invalid as well, ERROR-01 will be displayed.

#### **4.8 Store function**

Depending on the programming of PAR-05 the displayed value is not changing for as long as the store input is active. The store input has no function when PAR-04 = 1xx.

## 5 OUTPUTS

### 5.1 Output programmed as cam

Output 1 : Preset 1 and 2 (see table 1)

Output 2 : Preset 3 and 4 (see table 2)

**Table 1**

PAR-09	OUTPUT 1 HIGH IN CASE:
X1	counter $\geq$ preset 1 and $<$ preset 2
X2	counter $<$ preset 1 and $\geq$ preset 2
X3	counter $\geq$ preset 1
X4	counter $<$ preset 1

**Table 2**

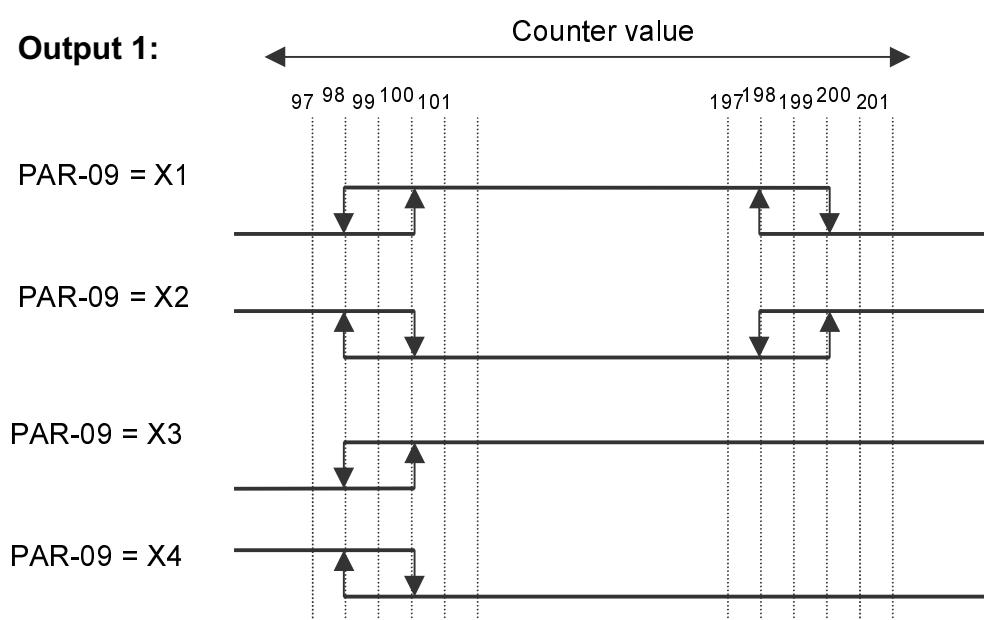
PAR-09	OUTPUT 2 HIGH IN CASE:
1x	counter $\geq$ preset 3 and $<$ preset 4
2x	counter $<$ preset 3 and $\geq$ preset 4
3x	counter $\geq$ preset 3
4x	counter $<$ preset 3

#### 5.1.1 Example

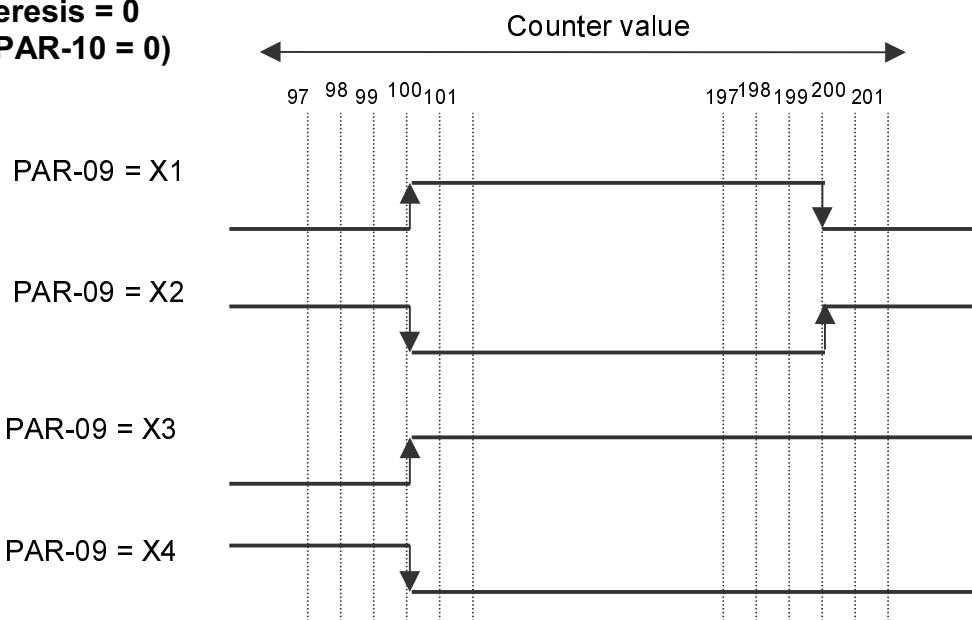
Preset 1 = 100 (start)

Preset 2 = 200 (end)

PAR-10 = 2 (hysteresis)



**Output 1, hysteresis = 0  
(PAR-10 = 0)**



## 5.2 Output programmed as pulse

Output 1 : Preset 1 (see table 3)

Output 2 : Preset 3 (see table 4)

**Table 3**

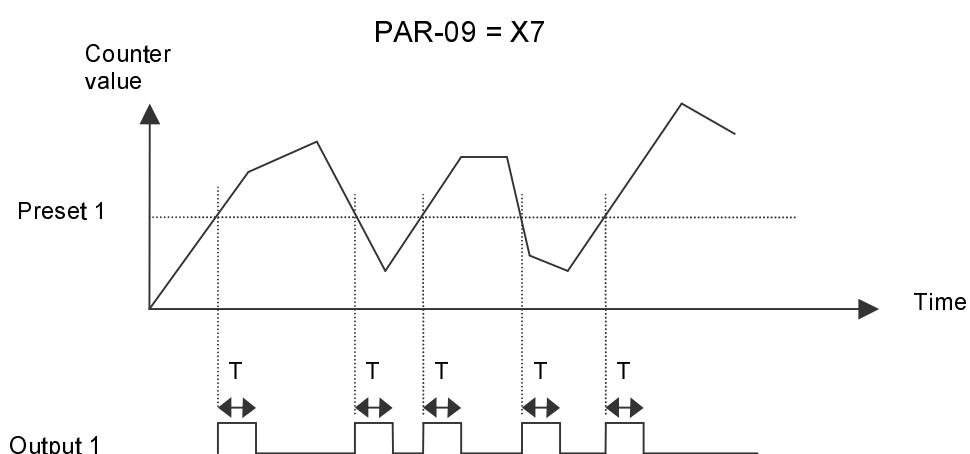
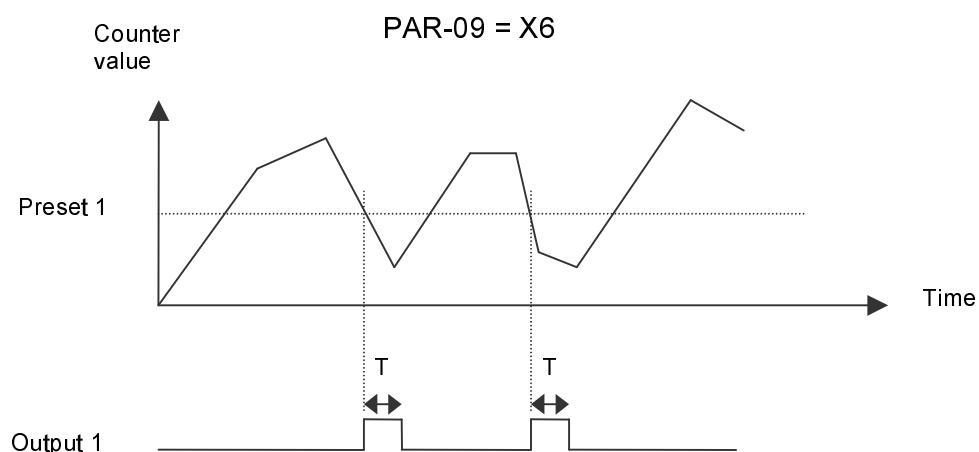
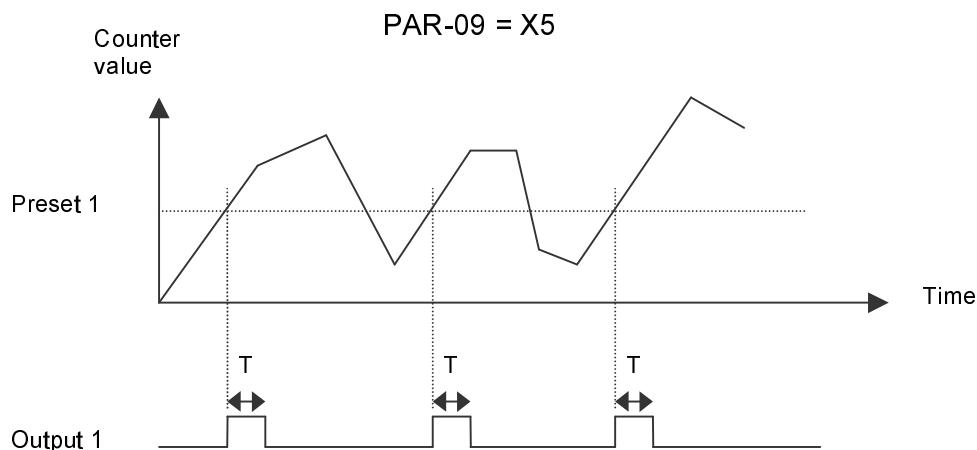
<b>PAR-09</b>	<b>OUTPUT 1 WILL GENERATE A PULS IN CASE:</b>
X5	counter becomes $\geq$ preset 1
X6	counter becomes $\leq$ preset 1
X7	counter becomes $\geq$ preset 1 or counter becomes $\leq$ preset 1

**Table 4**

<b>PAR-09</b>	<b>OUTPUT 2 WILL GENERATE A PULS IN CASE:</b>
5X	counter becomes $\geq$ preset 3
6X	counter becomes $\leq$ preset 3
7X	counter becomes $\geq$ preset 3 or counter becomes $\leq$ preset 3

### 5.2.1 Example

Only after the duration of the pulse a new pulse can be triggered. The duration is programmed in PAR-11.

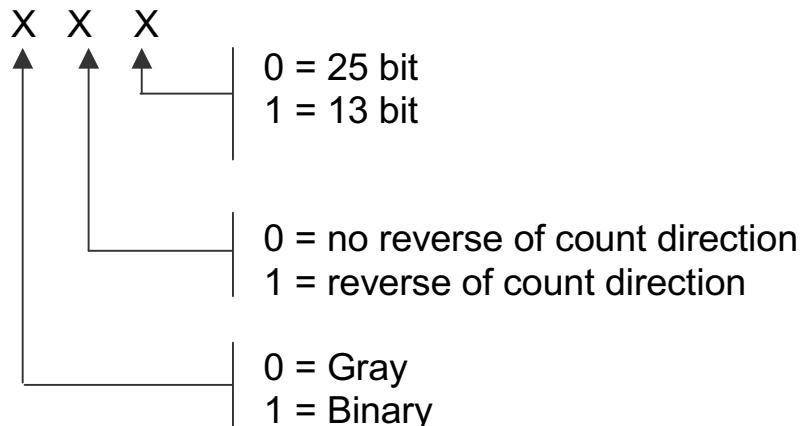


**APPENDIX A: PARAMETERS****PAR-01 ZERO-SHIFT**

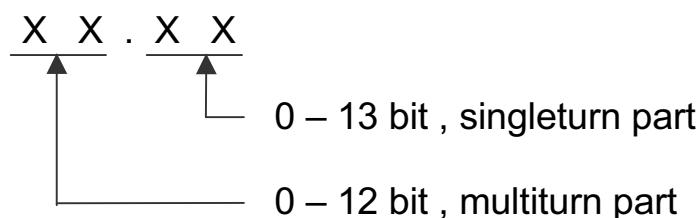
XXXXXXX -9999999 ... +9999999

**PAR-02 SSI-DETECTION AND DIRECTION**

XXX

**PAR-03 MULTIPLICATOR**XXXXXXX 0.000001 – 9.999999  
(input 0 = x1)**PAR-04 NUMBER OF BITS**

XXXX

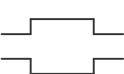
**PAR-05 STORE**

X

0 = no function

1 = high active

2 = low active



**APPENDIX A: PARAMETERS****PAR-06 DECIMAL POINT**

- X            0 = no decimal point  
          1 = X.X  
          2 = X.XX  
          3 = X.XXX  
          4 = X.XXXX  
          5 = X.XXXXX  
          6 = X.XXXXXX

**PAR-07 ADJUSTMENT VALUE**

XXXXXXXXX      -9999999....+99999999

**PAR-08 FUNCTION INPUT**

- X            0 = no function  
          1 = ZERO SET, rising edge  
          2 = ZERO-SET, falling edge  
          3 = lock programming mode parameters if function-input = low  
          4 = lock programming mode parameters and presets if function-input = low

**PAR-09 OUTPUT 1 AND 2**

XX



- 0 = no function  
1 = cam        
2 = cam        
3 = counter value >= preset  
4 = counter value < preset  
5 = pulse if counter value becomes >= preset  
6 = pulse if counter value becomes <= preset  
7 = both the functions 5 and 6

## **APPENDIX A: PARAMETERS**

### **PAR-10 HYSTERESIS OUTPUT 1 AND 2 (IF PAR-09 = 1..4)**

XXXXXXX      0 – 9999999  
(input 0 = no hysteresis)

### **PAR-11 DURATION PULSE OUTPUT 1 AND 2 (IF PAR-09 = 5..7)**

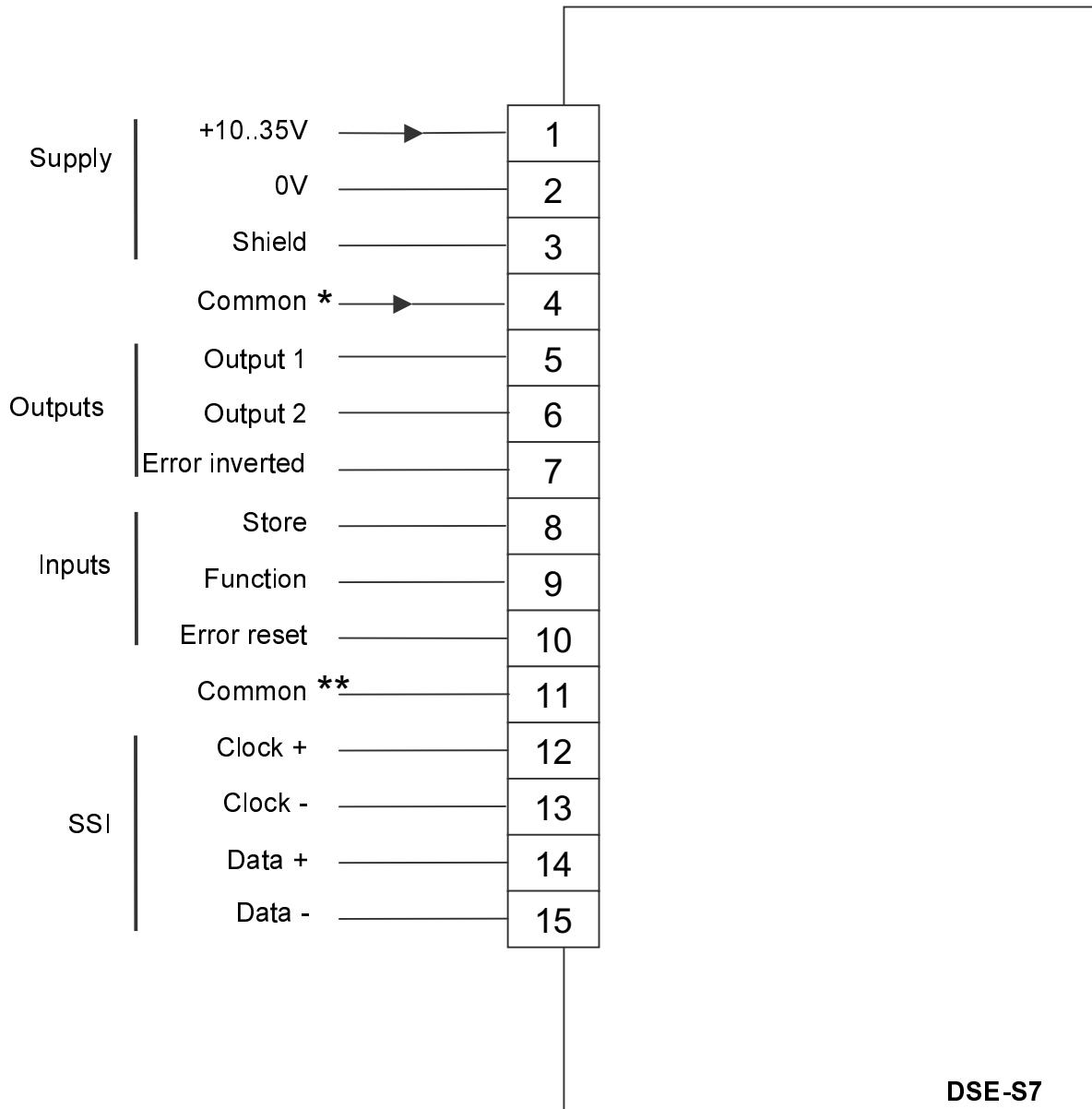
XXX      0.01 – 1.99 seconds  
(input in 0,01 second)

### **PAR-12 ADJUSTMENT TYPE**

X      0 = no function  
      1 = through PAR-07  
      2 = ZERO-SET

### **PAR-13 SSI-ERROR DETECTION**

X      0 = active  
      1 = inactive

**APPENDIX B: CONNECTIONS**

\* Signal supply for outputs

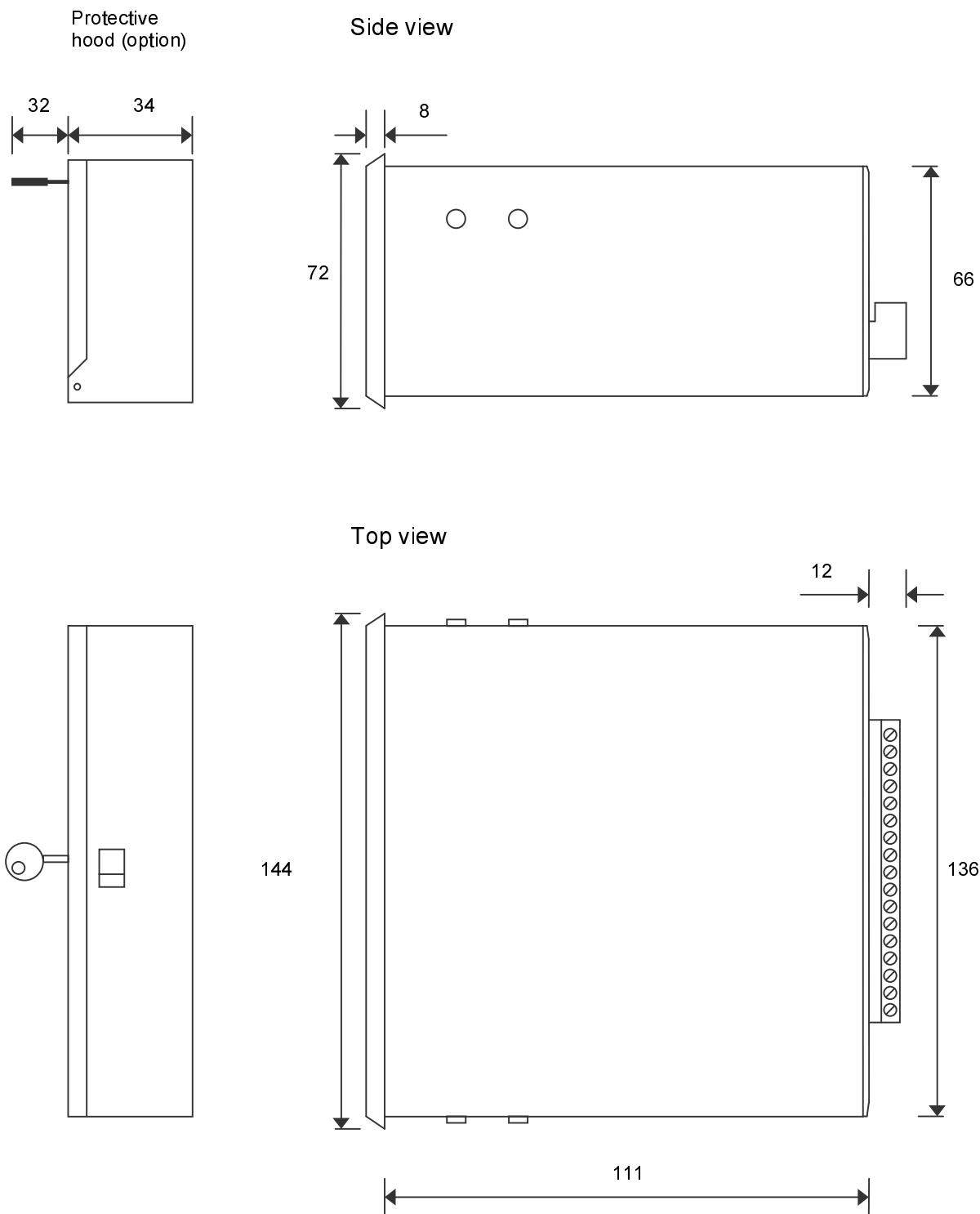
\*\* 0V for inputs

**APPENDIX C: TECHNICAL DATA**

- Supply voltage	10...35V DC (power failure protection not active)
current consumption	< 150mA (without load)
- SSI	
data input	opto-coupler acc. RS422
clock output	driver acc. RS422
clock frequency	125 kHz
- Inputs	optically isolated low: 0...+5V high: +10V...+35V input resistance appr. 1,8K Ohm at 24V
- Outputs	optically isolated, NPN transistor, open emitter with PTC
I <sub>max</sub>	50mA
Supply voltage	35V max.
Output voltage	supply voltage -3.50V (at 50mA) -2V (at 20mA)
- Count range	99999999...-9999999
- Cycle time	1,66 ms
- Data memory	EEPROM
- Display height	8 digit 7-segment LED 14 mm
- Temperature range	0...50°C
- Weight	< 0.5 kg
- Protection	front IP50, using the protection hood IP54 rear IP20

**APPENDIX D: SIZES**

Sizes in mm.





Distributor: